

Location & Its Infrastructure:

towards dm-scale real-time consumer equipment

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New Observables in Computing:

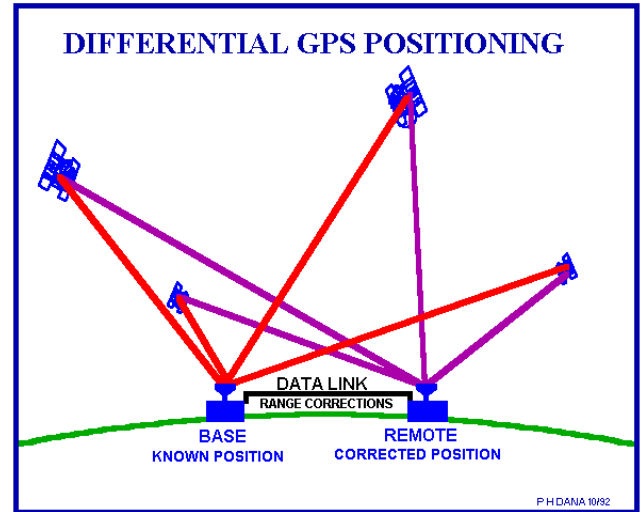
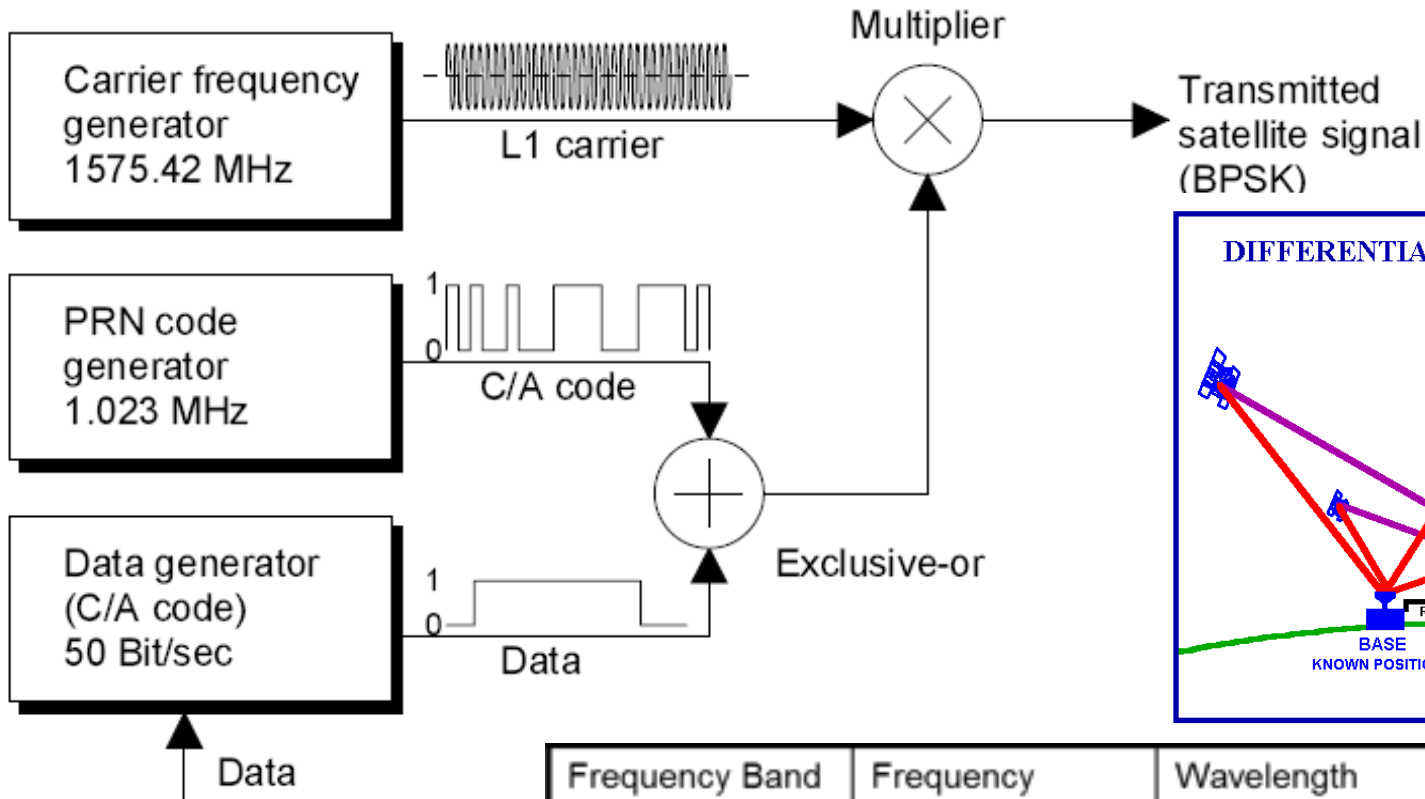
Sensor Networks, Cyber-Physical Systems

- Almost all computing was based on ‘storage’ as an observable
- Then ‘time’ happened
 - Real-time Systems
- Temperature, humidity, motion, proximity, ...
 - Sensor Networks, Cyber-physical Systems
- All physical phenomena are inherently local
 - Computing did have virtual mobility, sensors made it local (virtual versus physical places)
- **Computational Observables** are events or states that can in principle be detected by the programmer
- Mobility creates new observables
 - new hiddens (e.g., communication failure)
 - new security needs and opportunities (mobility across location, administrative domains).

Infospatial Objects



GPS 101



Frequency Band	Frequency	Wavelength (meters)	Expected accuracy (m)
L1	1575.43 MHz	0.190	0.0019
C/A	1.023 MHz	293	2.93

Location Infrastructure:

Accuracy, Determinism, Cost

- Who takes the measurement, who calculates the position?
 - (radar versus radio), server side finger-printing, client side Δ
 - From UltraS, IR, UWB radios (5-50cm) to TV signals, powerline, WiFi, Cellular (1m-100m)
- GPS infrastructure
 - Recreational, Navigational: 3m-10m. Consumer equipment bottomed out at 1-3m. (lane accuracy)
- Many forms of augmentation,.. to survey applications
 - First lock: 30-40 seconds, locking error: C/A 3m, P-code: 30 cm, atm. can add +/- 15m
 - DGPS with radio beacon assists: 1-3m, WAAS: 2m. Simple correctional data on position error.
 - RTK require RX capable of processing carrier-phase
 - AGPS (Cell, WiFi, IMU): many players to AGPS: 3GPP, OMA
- GPS Augmentations: many but real-time is a challenge/WIP
 - NDGPS – Ground-based augmentation (coast guard), USCG beacons sending RF signals
 - WAAS – Satellite based (air force): grid of 5x5 continental stations, 2 master stations
 - CORS – NOAA tied to National Spatial Reference Systems
 - Global Differential GPS (GDGPS) – JPL for real-time positioning, tied to TDRSS
 - IGS – International GNSS Service (one hour latency bound from measurement to broadcast)
- Commercially: SiRFstarV (Quad-GNSS+MEMS+AGPS), iOS (C/A + Cell Δ + WiFi), GLOBALCORS using iCORS





Sub-dm real-time consumer is on the horizon.

Getting to Sub-dm in Real-time Consumer Equipment

- Assisted by reference stations, rovers and cooperative infrastructure
 - DGPS: L1 corrections, range: 200-400km, meter level accuracy, few seconds, continental coverage
 - RTK – single base-station : L1 code, L1/L2 carrier corrections, range: 10-15 km, cm level accuracy, < 1 second delay, regional and local coverage.
- Not a new idea here: systems implementation may be
 - Stream corrections over the internet (RAW, RTCM, RTCA, SP3, RINEX)
 - NTRIP (RTCM via IP) – generic stateless protocol on HTTP/1.1 (RTCM-104)
 - Internet RTK using NRTIP demonstrated at 3cm/8cm (H/V) at 95% @GNSS'04.
 - SWEPOS at 1m accuracy using DGPS: correctional data on FM radio at 300 bytes/sec
 - Reference stations: Virtual versus Broadcast
 - One reference station works as a central unit collecting data from all stations in the network. Billable.
- Dm accuracy in real-time can be used for
 - Land surveying, Remote sensing, Hydrography, Machine control (precision agriculture), Emergency response, Asset inventory, Structural integrity monitoring, Atmospheric monitoring, weather forecasting, Tsunami and volcanic warning systems.

GPS Satellites



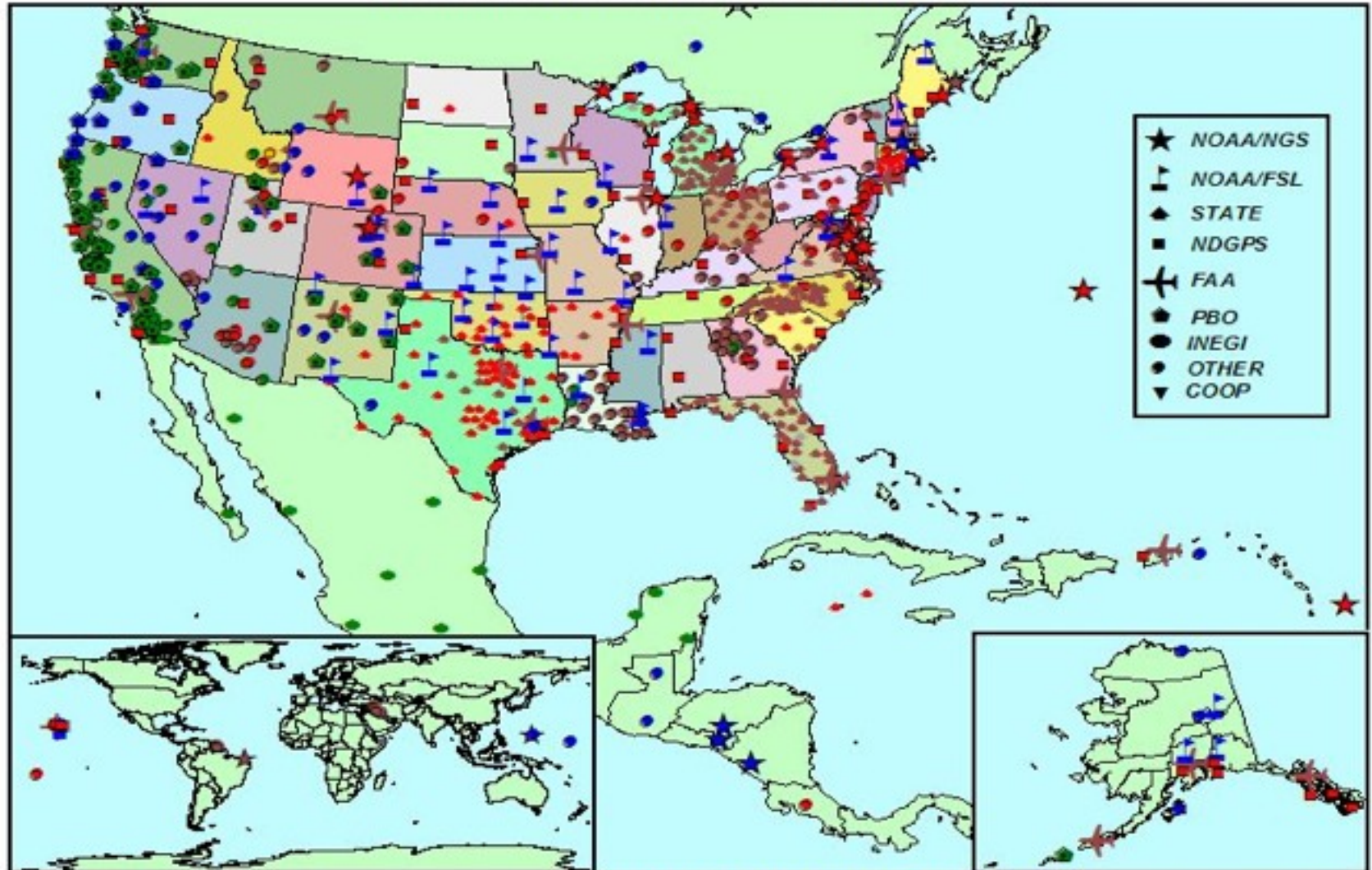
-  **Wide-area Reference Station (WRS)**
-  **New WRS's**
-  **Wide-area Master Station (WMS)**
-  **Ground Earth Station**

GEO Satellite

GEO Satellite

Continuously Operating Reference Stations

National CORS Network - April 2006

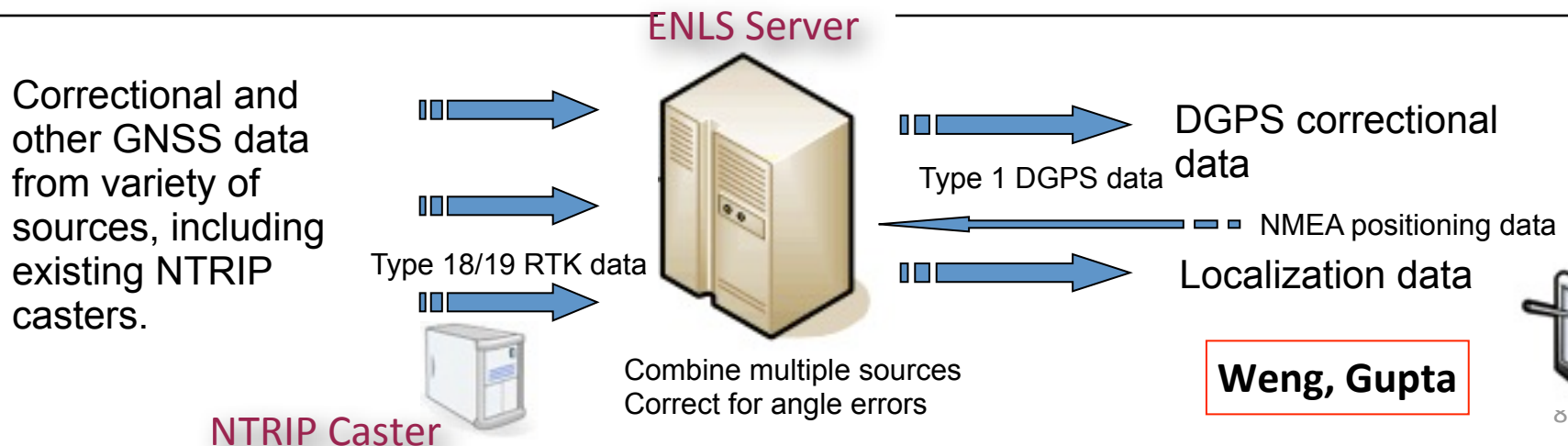


Symbol color denotes sampling rates: (1 sec) (5 sec) (10 sec) (15 sec) (30 sec) (Decommissioned)

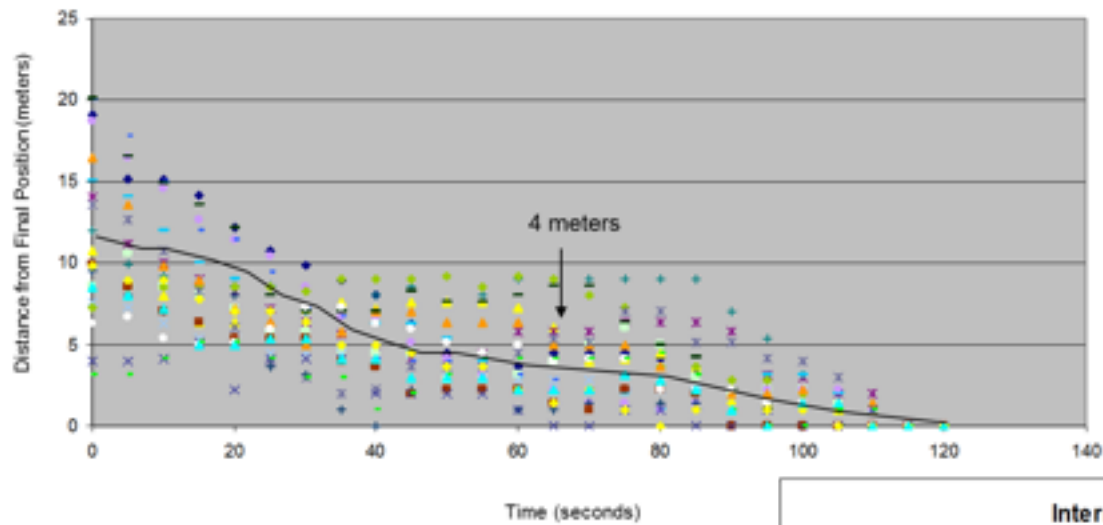
Craig 4/13/2006

Enhanced Network Localization Services (ENLS)

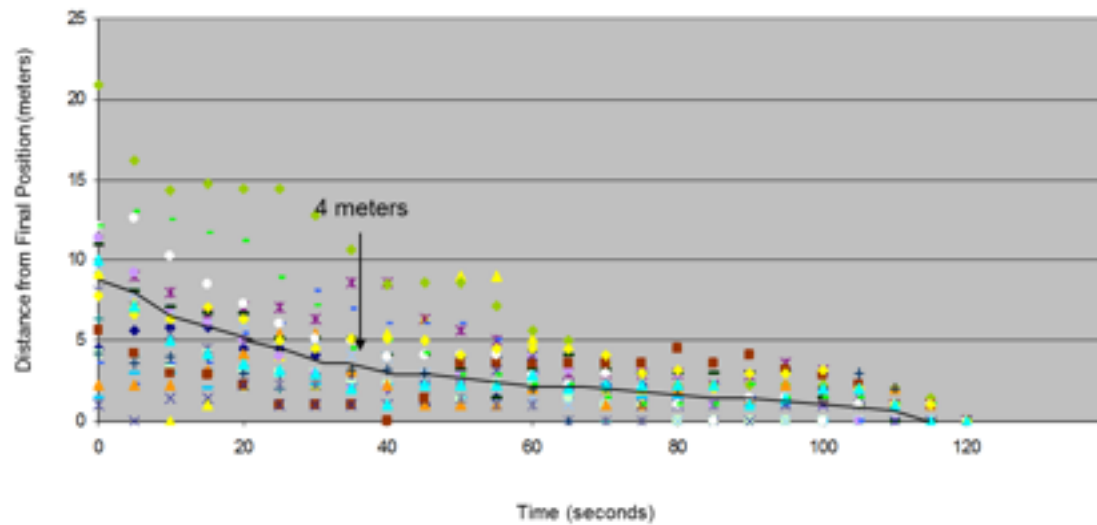
- ENLS provides a platform for delivery of localization services to end users.
- Two types of services:
 - Augmentation based services – deliver improved differential corrections over network from existing correction services, though VRS for DGPS and AGPS streams.
 - Localization based services – deliver localization information, such as transformed coordinates or GNSS data.
- APIs allow new modules to be written and incorporated with the ENLS server.
- Modules use network communication via TCP/IP ports to pass data. This allows for a more scalable infrastructure
- IPv6 embedded with localization information.
- Current project and implementation at enls.ucsd.edu.



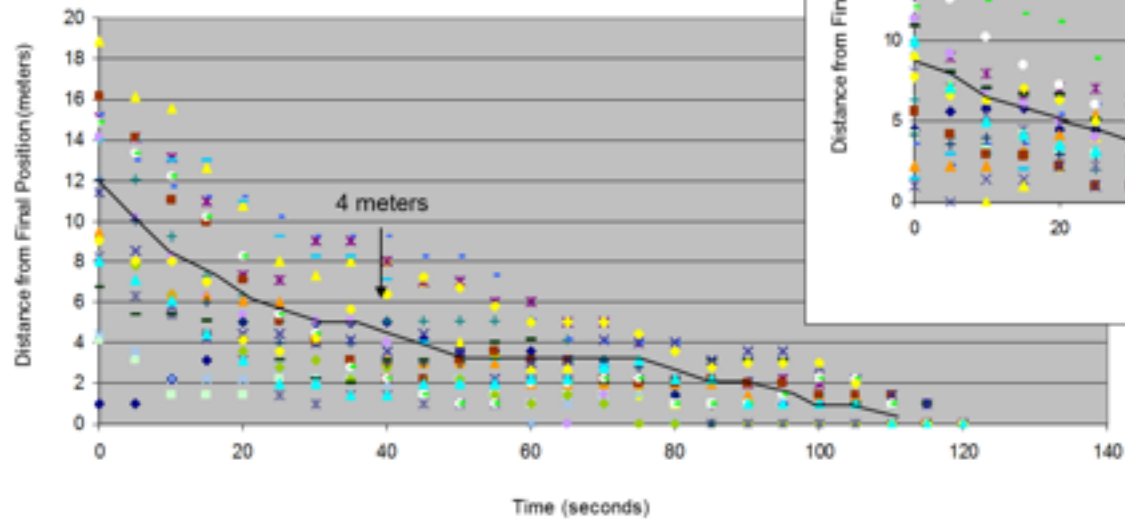
Non-Augmented Positional Error vs. Final Position



Internet Augmented Positional Error vs. Final Position



WAAS Augmented Positional Error vs. Final Position



Thoughts

- Consumer localization technologies have reached a (temporary?) plateau (automotive, application level): cultural problem?
 - Tremendous possibilities as we move to cm/dm real-time starting with networked DGPS at sub-meter.
- What role will Spatial Computing play in our lives in 2020?
- New observable that serves as
 - Organizer for contextual information
 - E.g., seamless interaction, continued operation across devices & spaces.
 - Authentication (ID), Security (Access control), Privacy (Spoofing)
 - A new root of trust (ROT) to ensure enforceable policies and observable violations. (part of shared secret, as a cryptographic key?)
- What are the most compelling transformative opportunities?
 - CPS-type applications driven by Spatio-Temporal Events.